# SERIES 50A SERVO AMPLIFIERS Models: 30A8, 25A20, 50A8, 50A20

ADVANCED

BRUSH TYPE

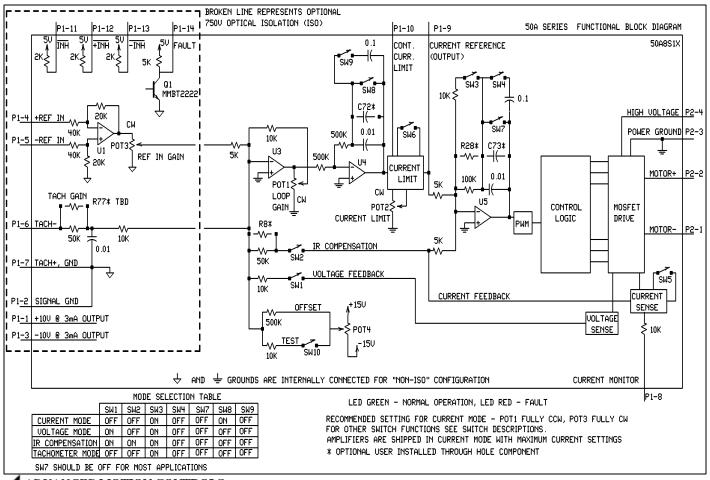
PWM SERVO

### FEATURES:

- Surface-mount technology
- Small size, low cost, ease of use
- Optional input signal isolation for off-the-rectified 120 VAC line operation
- DIP switch selectable: current, voltage, velocity, IR compensation, analog position loop
- Four quadrant regenerative operation
- Agency Approvals:



## **BLOCK DIAGRAM:**



ADVANCED MOTION CONTROLS 3629 Vista Mercado, Camarillo, CA 93012

Tel: (805) 389-1935, Fax: (805) 389-1165

### 50A Series

**DESCRIPTION:** The 50A Series PWM servo amplifiers are designed to drive brush type DC motors. A single red/green LED indicates operating status. All models are fully protected against over-voltage, over-current, over-heating and short-circuits across motor, ground and power leads. All models interface with digital controllers or can be used as a standalone drive. They require only a single unregulated DC power supply. Loop gain, current limit, input gain and offset can be adjusted using 14-turn potentiometers. The offset adjusting potentiometer can also be used as an on-board input signal for testing purposes when SW10 (DIP switch) is ON.

## SPECIFICATIONS:

|  | MODELS                                   |            |           |            |  |
|--|--|------------|-----------|------------|--|
| POWER STAGE SPECIFICATIONS                     | 30A8                                     | 25A20      | 50A8      | 50A20      |  |
| DC SUPPLY VOLTAGE                              | 20 - 80 V                                | 40 - 190 V | 20 - 80 V | 40 - 190 V |  |
| PEAK CURRENT (2 sec. max., internally limited) | ± 30 A                                   | ± 25 A     | ± 50 A    | ± 50 A     |  |
| MAX. CONTINUOUS CURRENT (internally limited)   | ± 15 A                                   | ± 12.5 A   | ± 25 A    | ± 25 A     |  |
| MINIMUM LOAD INDUCTANCE*                       | 200 µH                                   | 250 µH     | 200 µH    | 250 µH     |  |
| SWITCHING FREQUENCY                            | 22 kHz ± 15%                             |            |           |            |  |
| HEATSINK (BASE) TEMPERATURE RANGE              | $0^{\circ}$ to +65°C, disables if > 65°C |            |           |            |  |
| POWER DISSIPATION AT CONTINUOUS CURRENT        | 60 W                                     | 125 W      | 100 W     | 250 W      |  |
| OVER-VOLTAGE SHUT-DOWN (self-reset)            | 86 V                                     | 195 V      | 86 V      | 195 V      |  |
| BANDWIDTH (load dependent)                     | 2.5 kHz                                  |            |           |            |  |

| MECHANICAL SPECIFICATIONS       |                           |  |  |  |
|---------------------------------|---------------------------|--|--|--|
| POWER CONNECTOR Screw terminals |                           |  |  |  |
| SIGNAL CONNECTOR                | Molex connector           |  |  |  |
| SIZE                            | 7.35 x 4.40 x 1.00 inches |  |  |  |
|                                 | 186.7 x 111.7 x 25.4 mm   |  |  |  |
| WEIGHT                          | 1.5 lb.                   |  |  |  |
|                                 | 0.68 kg                   |  |  |  |

\* Low inductance motors ("pancake" and "basket-wound") require external inductors.

# **PIN FUNCTIONS:**

| CONNECTOR | PIN | NAME                        | DESCRIPTION / NOTES   | I/O  |  |  |  |
|-----------|-----|-----------------------------|---|------|--|--|--|
|           | 1   | +10 V OUT                   |   | 0    |  |  |  |
|           | 2   | SIGNAL GND                  | Provides regulated voltages of ±10 V @ 3 mA for customer use. Short circuit protected.  | SGND |  |  |  |
|           | 3   | -10 V OUT                   |   | 0    |  |  |  |
|           | 4   | +REF IN                     | Differential analog input, max ±15 V, 40K input   |      |  |  |  |
|           | 5   | -REF IN                     | resistance.   | I    |  |  |  |
|           | 6   | -TACH IN                    |   |      |  |  |  |
|           | 7   | +TACH (SGND)                | Maximum ±60 V analog, 60K input resistance.   | I    |  |  |  |
|           | 8   | CURRENT<br>MONITOR OUT      | This signal is proportional to the actual current in the motor leads. Scaling is 4A/V (2A/V when SW5=OFF) for 30A8 and 25A20; and 6A/V (3A/V when SW5 = OFF) for 50A8 and 50A20.  | 0    |  |  |  |
| 10        |     | REFERENCE                   | Command signal to the internal current-loop. The maximum peak current rating of the amplifier always equals 7.25 V at this pin. See current limit adjustment information below.   |      |  |  |  |
|           |     | CONTINUOUS<br>CURRENT LIMIT | Can be used to reduce the factory-preset maximum<br>continuous current limit. See current limit adjustment<br>information below. This is only an option on non-isolated<br>units. This pin is reserved on isolated units.   |      |  |  |  |
|           | 11  | INHIBIT                     | This TTL level input signal turns off all four power devices<br>of the "H" bridge drive when pulled to ground. This inhibit<br>will cause a FAULT condition and a red LED. For inverted<br>inhibit inputs; see section "G". | I    |  |  |  |
|           | 12  | +INHIBIT                    | Disables the amplifier for the "+" direction only. This inhibit will not cause a FAULT condition or a red LED.  |      |  |  |  |
|           | 13  | -INHIBIT                    | Disables the amplifier for the "-" direction only. This inhibit will not cause a FAULT condition or a red LED.  |      |  |  |  |
|           | 14  | FAULT OUT<br>(red LED)      | TTL compatible output. It becomes high during output short-circuit, over-voltage, over-heating, inhibit, and during "power-on reset". Fault condition indicated by red LED.   |      |  |  |  |
|           | 15  | SYNCH IN                    | Used for synchronizing the switching frequency of several amplifier modules. Consult factory for this option. Not   | N/A  |  |  |  |
|           | 16  | SYNCH OUT                   | applicable for "ISO" option. On the "ISO" option pin 16 is<br>connected to power ground and can be used as ground<br>with P1-8 and P1-9. Pin 15 is reserved on "ISO" units.   |      |  |  |  |
|           | 1   | - MOTOR                     | Motor minus connection.   | 0    |  |  |  |
| 50        | 2   | +MOTOR                      | Motor plus connection.  | 0    |  |  |  |
| P2        | 3   | POWER<br>GROUND             | Power Ground.   | PGND |  |  |  |
|           | 4   | HIGH VOLTAGE                | DC voltage input.   | I    |  |  |  |

# SWITCH FUNCTIONS:

|        |  | SETTING   |  |  |  |
|--------|--|---|--|--|--|
| SWITCH | FUNCTION DESCRIPTION   | ON  | OFF  |  |  |
| 1      | Internal voltage feedback  | On  | Off  |  |  |
| 2      | Internal current feedback for IR compensation  | On  | Off  |  |  |
| 3      | Current loop gain  | Decrease  | Increase                                     |  |  |
| 4      | Current loop integration   | Increase  | Decrease                                     |  |  |
| 5      | Current scaling. When OFF, increases sensitivity of current sense thus reducing both peak and continuous current limit by 50% (see section "G"). | Full-current  | Half-current                                 |  |  |
| 6      | Can be used to reduce factory-preset maximum continuous current limit (see section "G").   | Cont./Peak<br>Ratio 25%   | Cont./Peak<br>Ratio 50%                      |  |  |
| 7      | It is recommended to leave SW7 in the OFF position.  | Shorts out the<br>current loop<br>integrator<br>capacitor                     | Current loop<br>integrator operating         |  |  |
| 8      | This capacitor normally ensures "error-free" operation by reducing the error-signal (output of summing amplifier) to zero.                       | Shorts out the<br>outer velocity /<br>voltage loop<br>integrator<br>capacitor | Velocity/<br>Voltage integrator<br>operating |  |  |
| 9      | Adjusts the value of the integrator capacitor. It is recommended to leave SW9 in the OFF position for most applications.                         | Increase  | Decrease                                     |  |  |
| 10     | Offset / test. Controls sensitivity of the "offset" pot.<br>Used as an on-board reference signal in test mode.                                   | Increase  | Decrease                                     |  |  |

# POTENTIOMETER FUNCTIONS:

| POTENTIOMETER | DESCRIPTION   | TURNING CW                           |
|---------------|---|--------------------------------------|
| Pot 1         | Loop gain adjustment in voltage & velocity modes. Turn this pot fully ccw in current mode.  | Increases loop<br>gain               |
| Pot 2         | Current limit. It adjusts both continuous and peak current limit by maintaining their ratio (50%).  | Increases current<br>limit           |
| Pot 3         | Reference gain. It adjusts the ratio between input signal and output variables (voltage, current, and velocity).  | Increases<br>reference input<br>gain |
| Pot 4         | Pot 4 Offset / test. Used to adjust any imbalance in the input signal or in the amplifier. When SW10 (DIP switch) is ON, the sensitivity of this pot is greatly increased thus it can be used as an on-board signal source for testing purposes. See section "G". |                                      |

### TEST POINTS FOR POTENTIOMETERS: See section "G".

**SET-UP:** See section "G" for engineering and installation notes.

### **OPTIONAL INPUT SIGNAL ISOLATION:**

These amplifiers can be ordered with an internally installed analog isolation amplifier, which optically isolates the inputs from the remainder of the amplifier circuitry ("ISO" option). See functional block diagram above. This optional input isolation facilitates off-the-rectified-line operation. Isolation is necessary in transformer-less applications to isolate controller signal ground (often the same as earth ground) from DC power ground. The isolation option may also reduce system noise. This option is generally not required with isolated power supplies.

### **OPERATING MODE SELECTION:**

These modes can be selected with the DIP switches according to the chart in the functional block diagram:

- Current Mode
- Voltage Mode
- IR Compensation Mode
- Tachometer Mode

See section "G" for more information.

### **APPLICATION NOTE:**

See section "G" for more information on analog position loop mode.

#### CURRENT LIMIT ADJUSTMENTS:

These amplifiers feature separate peak and continuous current limit adjustments.

The current limit adjusting Pot 2 adjusts both peak and continuous current limit at the same time. It has 12 active turns plus 1 inactive turn at each end and is approximately linear. Thus, to adjust the current limit, turn the potentiometer fully counter-clockwise then turn clockwise to the appropriate value. If the desired limit is, for example, 25 amperes, and the servo amplifier peak current is 50 amperes, turn the potentiometer 7 turns clockwise from the fully counter-clockwise position.

Pin P1-9 is the input to the internal current amplifier stage. Since the output current is proportional to P1-9, the adjusted current limit can easily be observed at this pin. Note that a command signal must be applied to the reference inputs to obtain a reading on P1-9. The maximum peak current value equals 7.25 V at this pin and the maximum continuous current value equals 3.63 V at this pin. If SW5=ON, peak rated amplifier current=7.25 V. If SW5=OFF, 1/2 peak rated amplifier current =7.25 V. Example using the 30A8 with SW5=ON, 30 A=7.25 V and with SW5=OFF, 15 A=7.25 V.

The actual current can be monitored at pin P1-8.

The continuous current limit can be reduced without affecting the peak current limit by connecting an external current limiting resistor R-Imt between P1-10 and P1-2. This option is only available on non isolated units. See table below.

| Current Limit Resistor $(\Omega)$ | 18K | 6.5K | 3.4K | 2.5K | 1.8K | 1K  | 800  | 300  | 0    |
|-----------------------------------|-----|------|------|------|------|-----|------|------|------|
| Continuous Current Limit %        | 90% | 80%  | 70%  | 65%  | 60%  | 50% | 45 % | 40 % | 30 % |

SW6 (DIP switch) will reduce the continuous current limit to 50% of the maximum value, when switched ON. SW5 (DIP switch) will reduce the current feedback (monitor) scaling by 50%, thereby reducing both the peak and the continuous current limit by 50%, when switched OFF.

TYPICAL SYSTEM WIRING: See section "G" .

### **ORDERING INFORMATION:**

Models: 30A8X, 25A20X, 50A8X, 50A20X

With isolation: 30A8IX, 25A20IX, 50A8IX, and 50A20IX

X indicates the current revision letter.

MOUNTING DIMENSIONS: See page F-9.